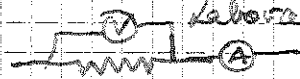
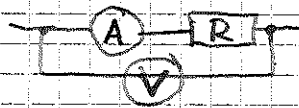


Montaje corto



largo



$$\frac{1}{R} = \frac{1}{R'} - \frac{1}{R_v} \rightarrow R' = \frac{R R_v}{R + R_v}$$

$$R = R' - R_A$$

$$R' = R + R_A$$

$$R' = \frac{V}{I}$$

$$V_1 I_1 = \frac{V_0 I_0}{\sqrt{2}}$$

Osc LEVEL → regula voltaje de inicio

SLOPE → cambia pendiente

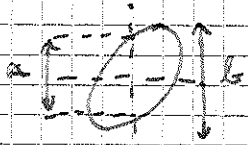
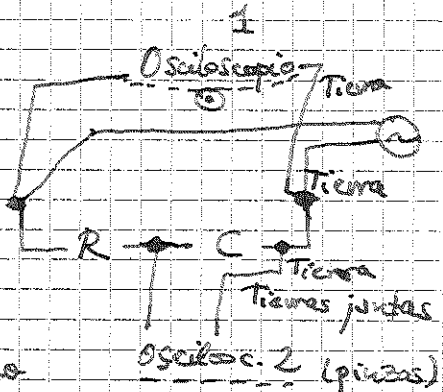
CHOP → + sincronizado

TRIG EXT → TTL / CMOS (aux out)

Calibrado → mando a la delta del todo

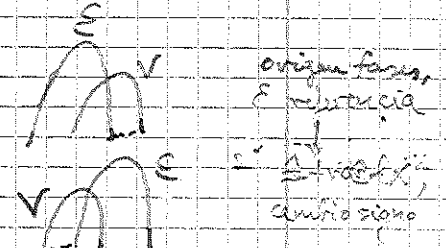
$$f = \frac{1}{T}$$

Centrar x-y pulsando GD



$$|\sin \Phi| = \frac{a}{b}$$

$\Phi = \phi_V - \phi_E \Rightarrow \phi_V$ si V adelantada
 $\Phi < 0$ si V adelantada
 $\Phi > 0$ si V retrasada



$$Z = t_{vE} - t_{vI} \rightarrow \text{sig}(Z) = \text{sig}(\Phi)$$

$$\Phi = \frac{2\pi Z}{T} = 2\pi f Z \quad (\pm 2n\pi)$$

$$\phi = \phi_2 - \phi_1$$

Alternancia

$$V_1 = V_{10} \sin(\omega t + \phi_1)$$

$$V_2 = V_{20} \sin(\omega t + \phi_2)$$

si $\Phi = \phi_E - \phi_V = -\phi_V$

$$\text{sig } \Phi = -\text{sig}(\phi_E - \phi_V)$$

$$= \text{sig}(\phi_V - \phi_E)$$

$$|V_g| = |Z| |I_g|$$

STOP

PRINT